TO DO LIST

ELECTRICAL / SOFTWARE

* Detection function working then testing for ramp and obstacles.
* Navigation algorithm working: Including the IMU and testing for the IMU.
* Discussion for the colour sensor testing.
* Stepper motor for base lifting
* Encoder motor implemented for the wheels and the collection mechanism

 MECHANICAL

* Top sensors need to be on the side of caution, above 100mm
* Recess the sensors into the bases
* Interlocked wheels: Overlay, fully printed, connection mechanism
* Mechanical design adjustment: adjust the range to be able to collect knocked over weights.
* Adjust the 3D printed materials for the stuff.
* Reverse sensor orientation sizes.